

# Neural Radiance Fields for Game Engines and Web Applications

## Converting Photos into 3D Assets for Real-time Rendering

# Fraunhofer Institute for Integrated Circuits IIS

Founded in 1985, >1,100 employees, budget of €167.9 Million

Locations in **Erlangen**, Nuremberg, Fürth, Dresden, Ilmenau, Munich, Bamberg, Waischenfeld, Coburg, Würzburg, Deggendorf and Passau.



# Fraunhofer IIS

## Audio and Media Technologies

With more than **30 years of experience**, Fraunhofer IIS is the world's most respected authority in low bit-rate, high-quality audio coding, signal processing and image coding

Over **300 employees**

Fraunhofer IIS has licensed its audio codec software to more than **2,000 companies**

Fraunhofer audio technology is integrated in virtually **all Consumer Electronics devices, PCs and smartphones**



# Agenda

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## Part 1: Overview of view-interpolation and 3D-reconstruction

- Motivation
- Technology landscape overview

## Part 2: Principles of Neural Radiance Fields (NERFs)

- Technical principles
- Relation to multi-view stereo
- Fundamental challenges

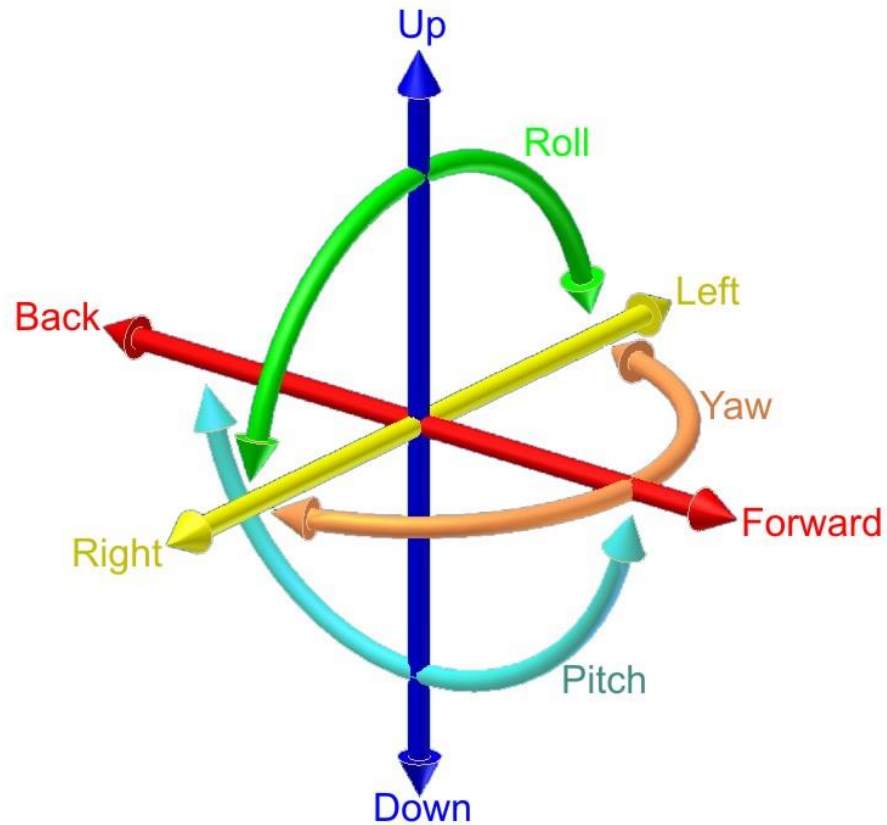
## Part 3: Neural Radiance Fields for Real-time Rendering

- Solution Approaches
- Voxel Meshes
- Integration into Game Engines and Web Applications

# Part 1: Overview of view-interpolation and 3D-reconstruction

# Motivation

Observation of a scene or an object with six degrees of freedom (6-DoF)



## 6DoF

- Archival, Documentation
- Remote control, assistance
- Entertainment (Gaming, virtual reality, movie creation)
- Presentation (e-commerce, advertisement)
- Planning & simulation
- ...

# Not only for VR

Observation of a scene or an object with six degrees of freedom (6-DoF)



# Problem formulation

Interpolate views between capture cameras

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# Geometry

## Solution aspects

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## View-dependent appearance

# Solution aspects

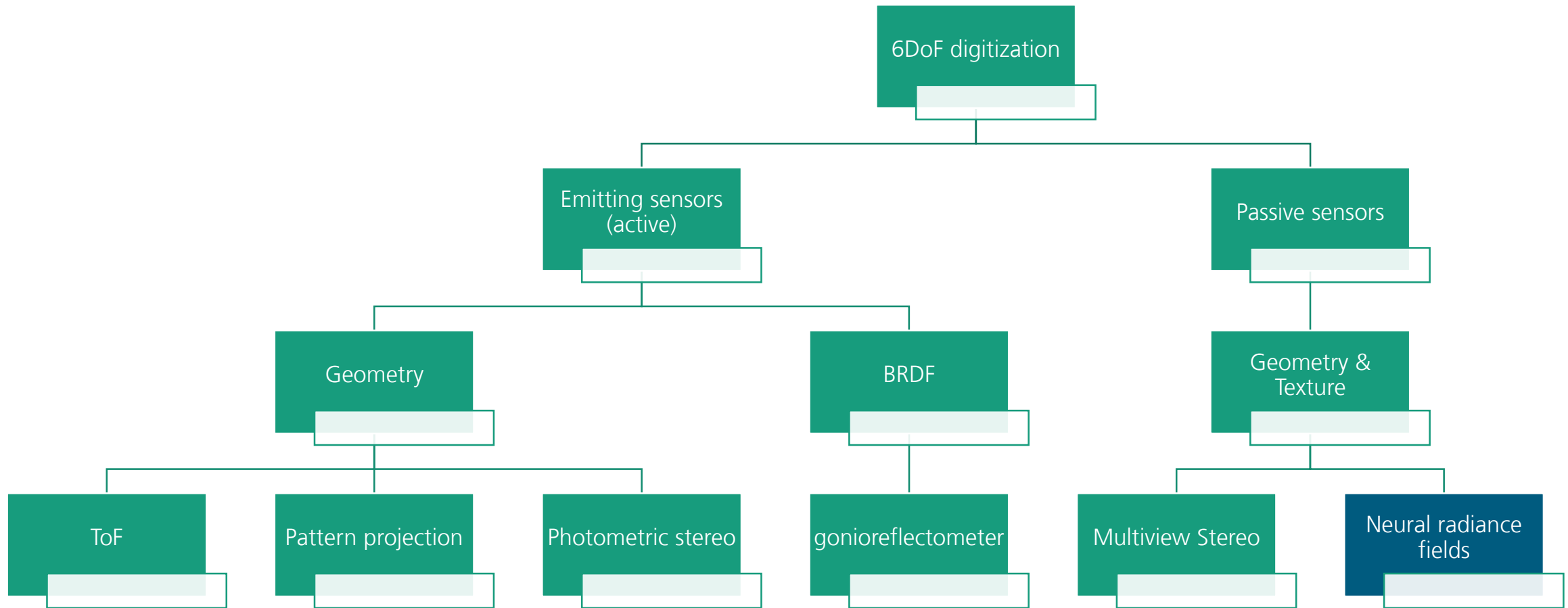
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**Know the color of an object point from every possible viewing direction**

Camera moves relative to constant car and light sources

# Selected technology landscape

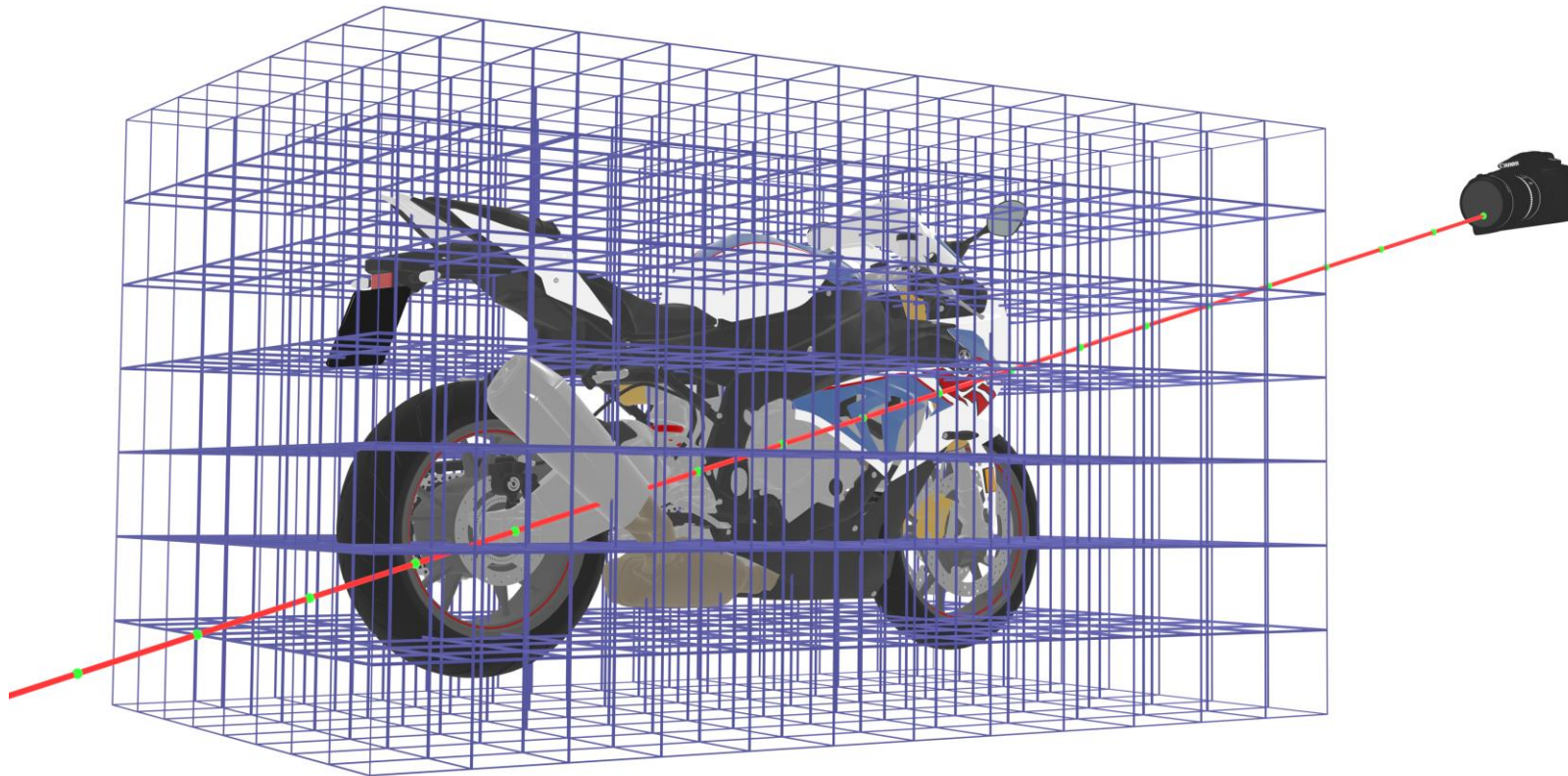


## Part 2: Principles of Neural Radiance Fields (NERFs)

# Neural radiance fields

## Technical principles

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### Approach

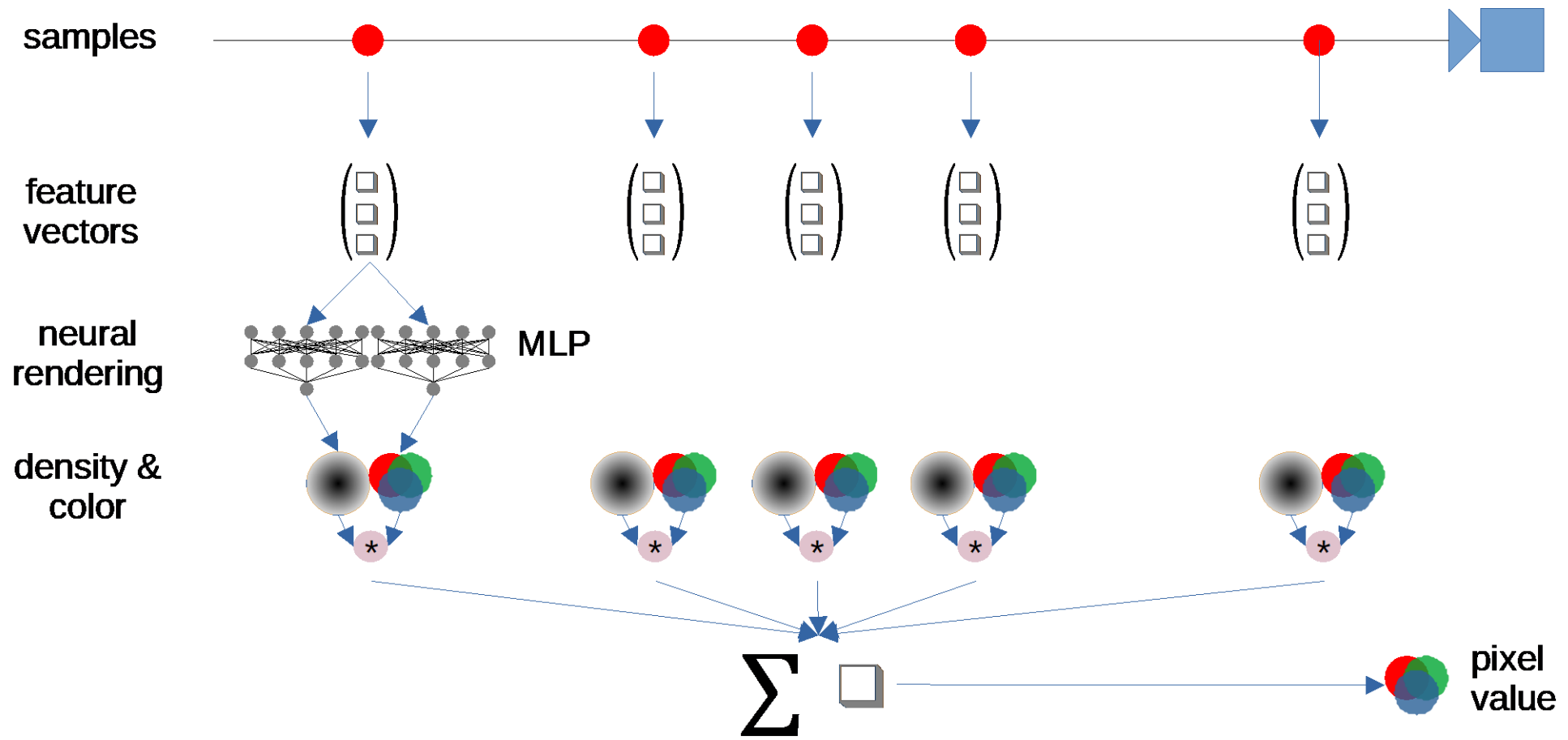
- Pixel based ray shooting
- Simulation of physical rendering
- Voxels contain
  - Density
  - Color
- Optimize voxel values to reproduce observed images

### AI contribution

- Massive progress in large scale optimization using GPUs
- Neural representation and rendering

# Algorithm architecture

## Schematic representation



## Relation and comparison with multi-view stereo

### Triangulation based on correspondences

- Known correspondences and camera parameters permit to compute position in space
- Determination of reliable correspondences difficult
- Noisy and incomplete point cloud



# Photogrammetry versus neural radiance fields

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## Photogrammetry

- Optimize for matching costs
  - Only indirectly optimize for visual appearance
- A single depth value per pixel
  - No support of transparent surfaces
- Generation of a Lambertian texture
  - No view dependent appearance
  
- Geometry driven

## Neural radiance fields

- Optimize for visual appearance directly
  - Leads to better quality
- Voxels may be semi-transparent
  
- Voxel color depends on viewing direction
  
  
- Appearance driven
  - Geometry extraction more difficult



Real-data (rendering only)

## Comparison with traditional methods

Early results



Voxel based reconstruction



Photogrammetry

Real-data (rendering only)

## Comparison with traditional methods

Early results



Voxel based reconstruction



Photogrammetry

# Comparison with traditional methods

## Summary

### Neural Radiance Fields (NERFs)

- Can deliver superior reconstruction quality
- But are not perfect neither



# Fundamental challenges

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## Memory consumption and compute time

### Photogrammetry

- Depth-map based
- Complexity  $O(n^2)$

### Neural radiance fields

- Voxel grid
- Complexity  $O(n^3)$

## Break in Workflow

- Optimization of appearance instead of consistent mesh
- Imposing mesh constraint may reduce overall quality

## Complex Optimizers

- Convergence not always granted

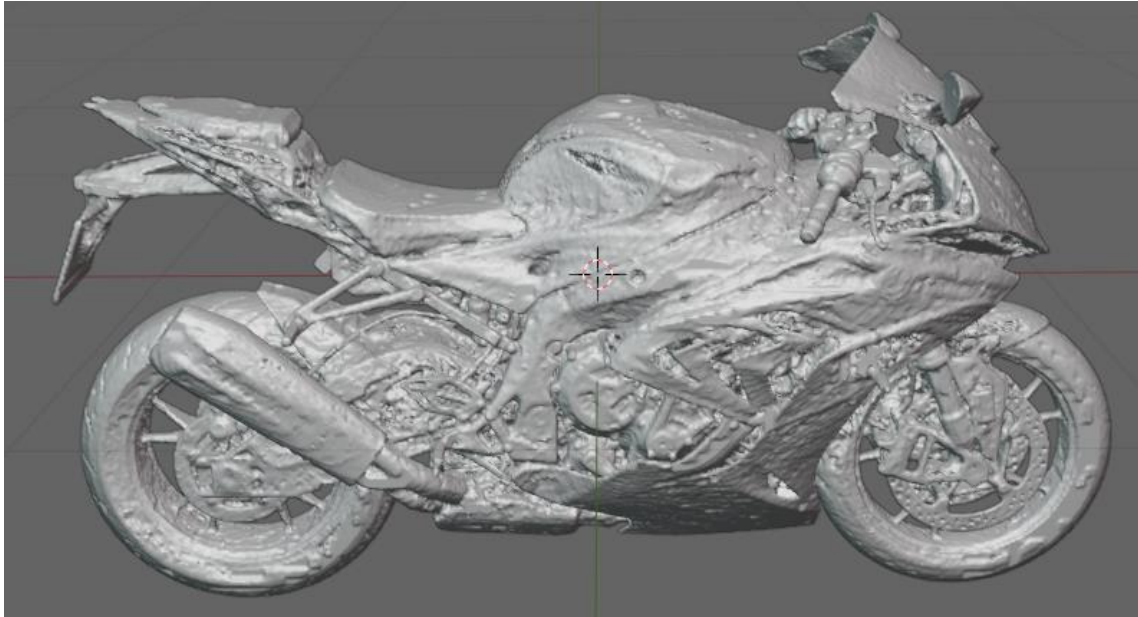
## Need of

- Good parameter heuristics
- Clean and consistent input data
- Clever reconstruction methods

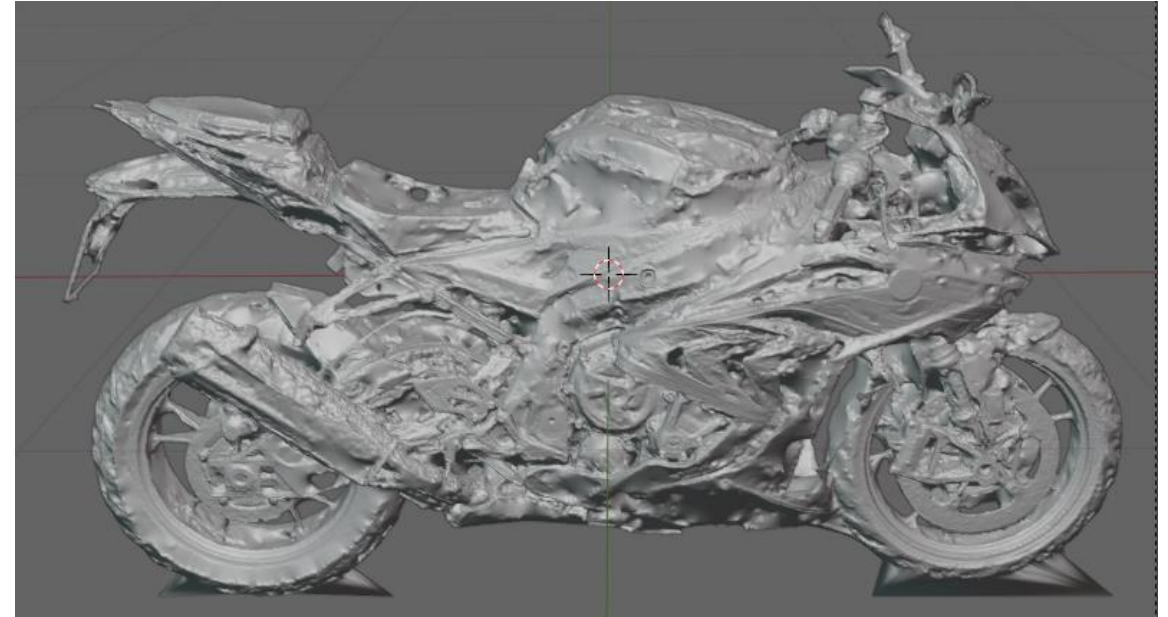
# Comparison with traditional methods

## On the geometry quality

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**Voxel based reconstruction**

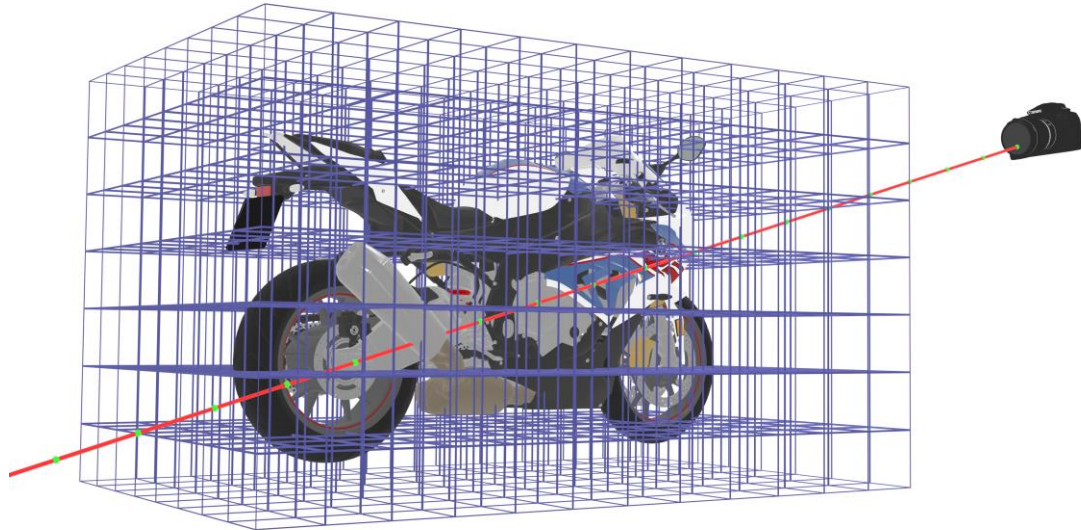


**Photogrammetry**

# Part 3: Neural Radiance Fields for Real-time Rendering

The fundamental problem

# Rendering Neural Radiance Fields (NERFs)



## Voxel rendering is slow

- For each ray, query all intersected voxels

## Tricks for speed-up

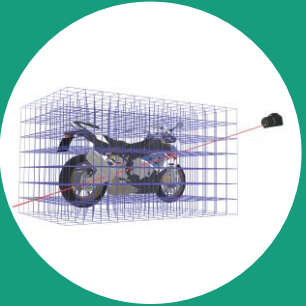
- Skip empty space
- Early ray termination

## Limitations

- NERFs reconstruction voxel clouds
- Lack of discrete geometry
- Requires to render multiple voxels per pixels

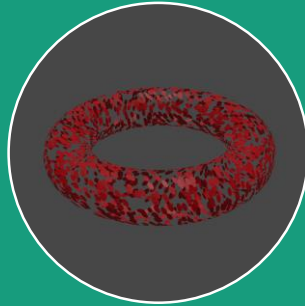
# Solution space

## Real-time rendering



### Optimize voxel rendering

- New rendering libraries
- New rendering hardware



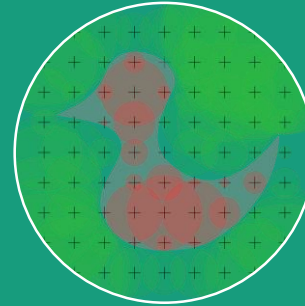
### Use of novel rendering primitives

- [Gaussian] splatting
- New rendering pipeline (i.e. due to tiling)



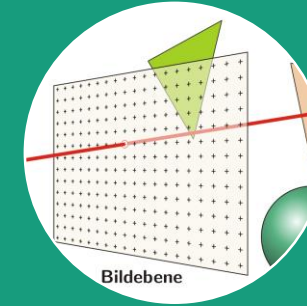
### Use of voxel meshes

- Generalized meshes



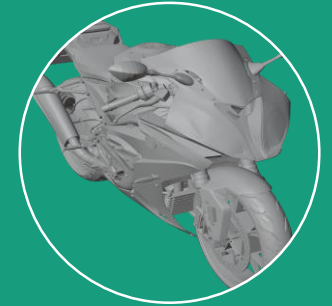
### Integrate surface constraints into NERFs

- i.e. signed distance fields
- Harder to converge
- No support of transparencies



### Direct mesh optimization (inverse rendering)

- Much harder to converge



### Convert voxels into meshes

- Loss of quality due to break in rendering principle



# Definition

## Voxel meshes

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### Definition

- Mesh with alpha and neural texture
- A neural renderer translates the neural colors into RGB values

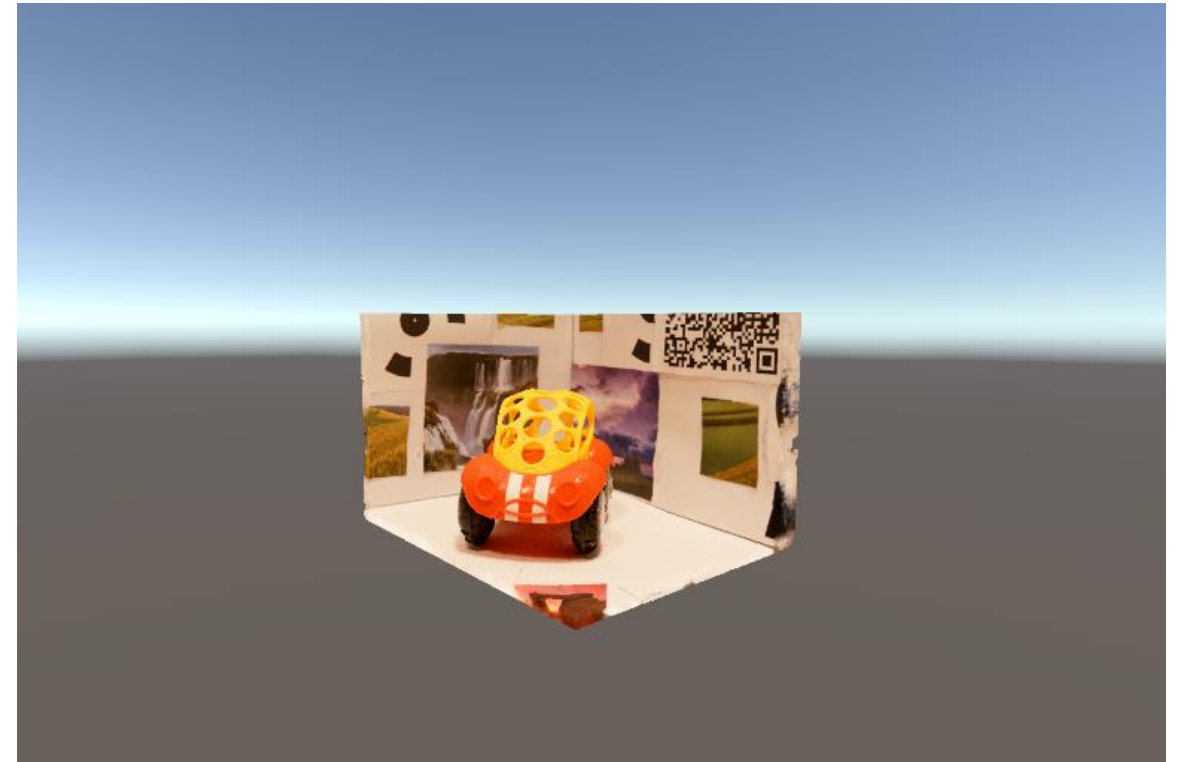
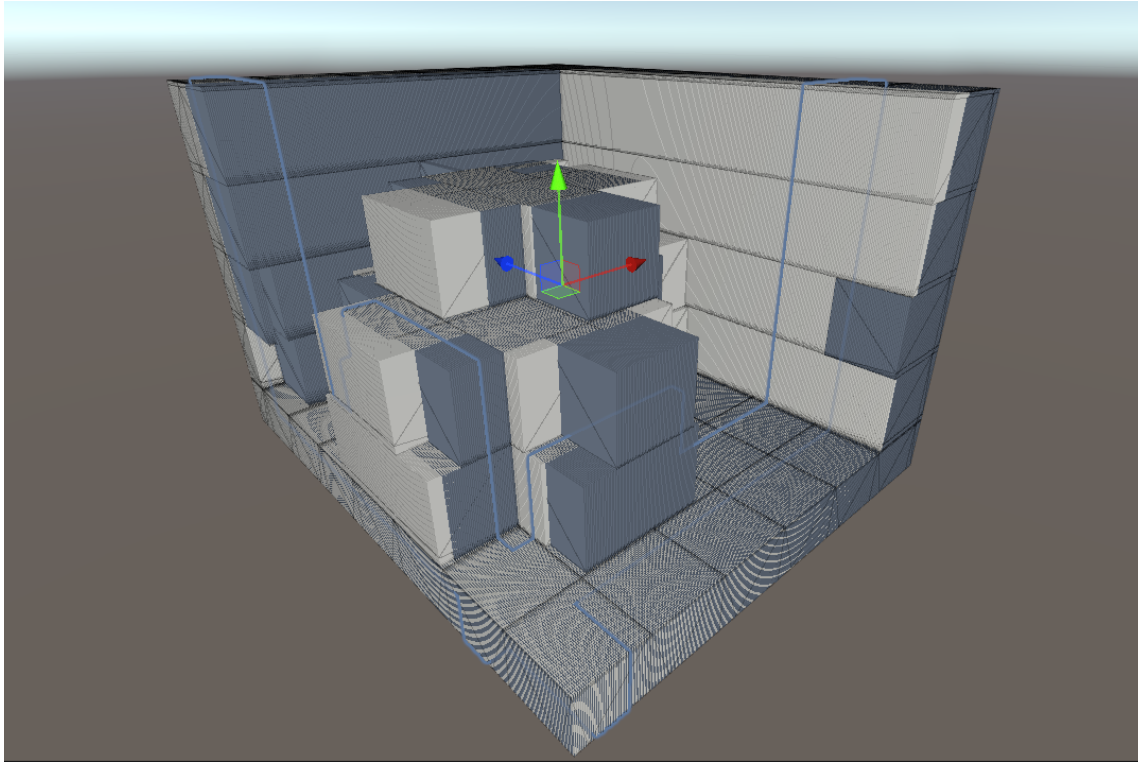
### Represent continuous voxel regions

- Only coarse representation of the geometry
- Details are handled by alpha and neural texture

# Example

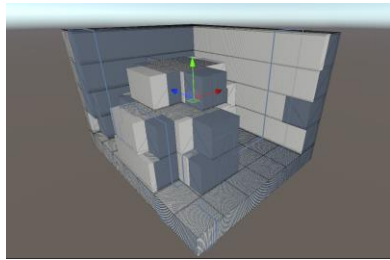
## Voxel mesh rendering

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# Voxel mesh rendering

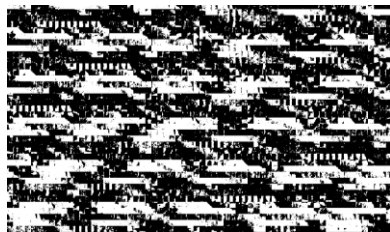
## Algorithm principle



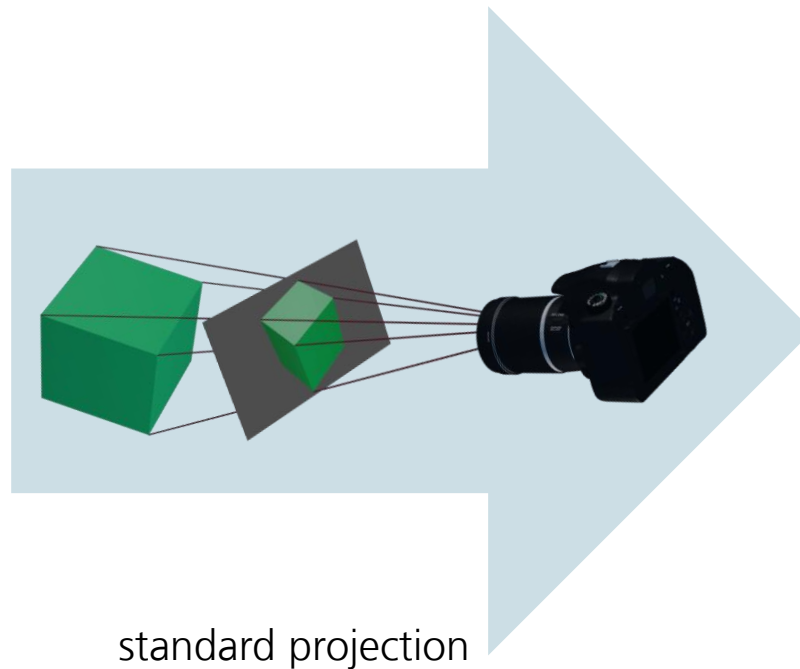
geometry



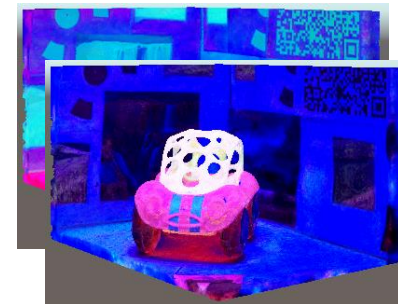
neural color texture



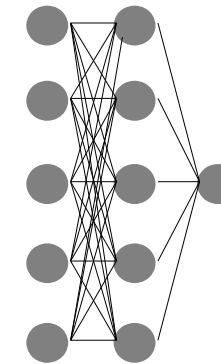
alpha texture



standard projection



neural image



MLP

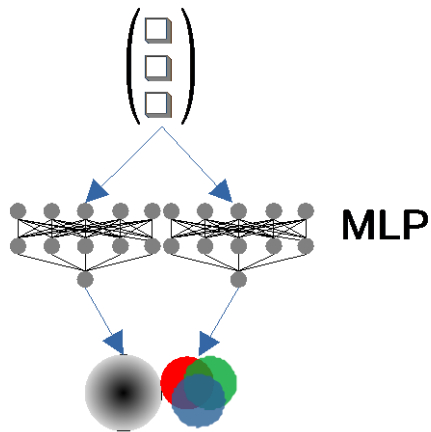


RGB image

## Real-time rendering in Unity

### UniTorch Plugin

- Integration of libTorch into Unity
- Highly optimized execution of MLP rendering
- Support of more powerful neural networks
- Interaction with different rendering passes to support different algorithm scenarios

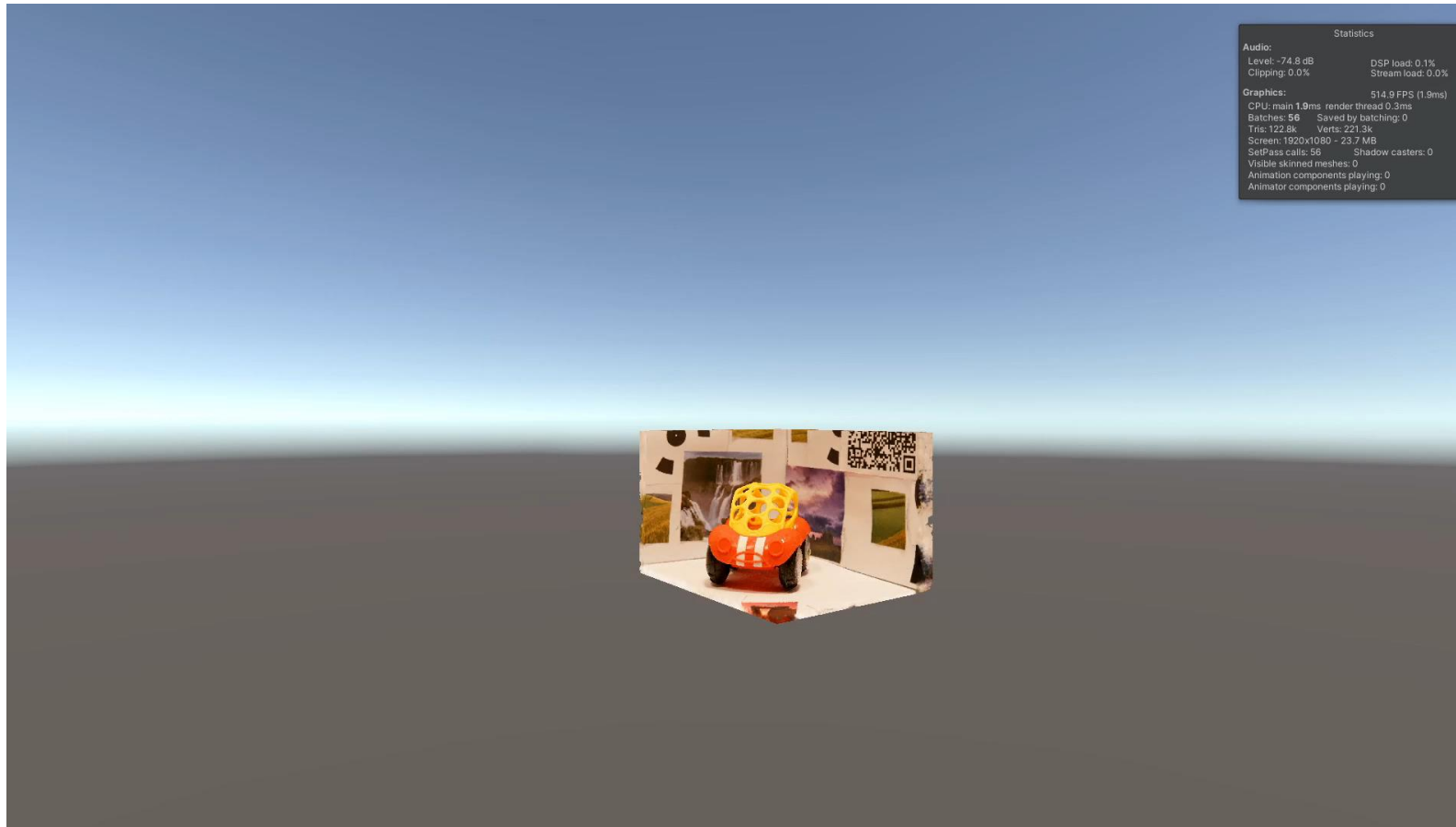


### Use of shader language

- Mostly platform independent
- Efficient integration into pixel rendering pipeline
  - Fragment/pixel shader
- Easier support of different Unity rendering pipelines
  - Standard Building Pipeline
  - Universal Rendering Pipeline
- Extension for Web applications possible

# Unity plugin for voxel mesh rendering

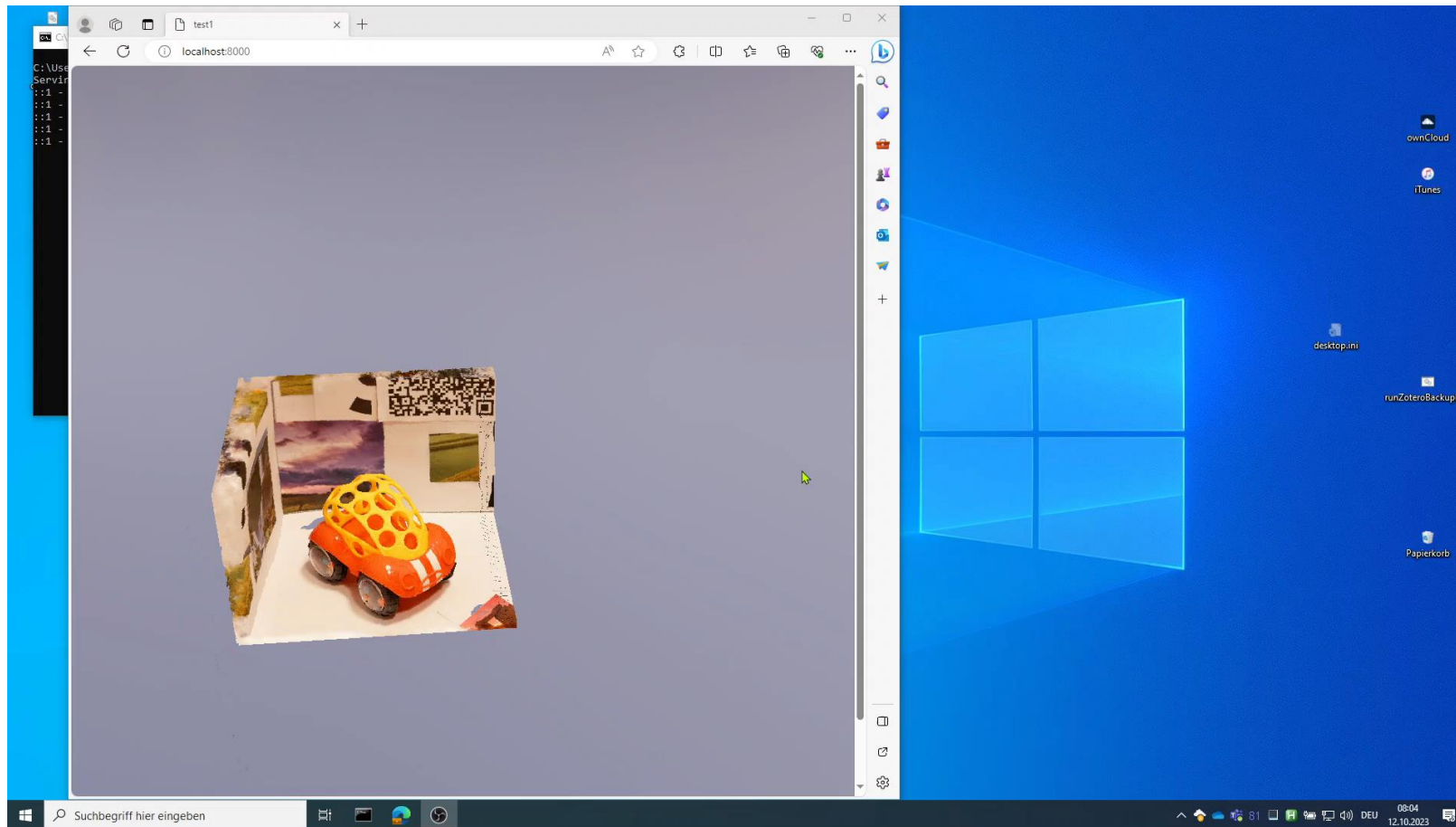
Result video for shader-based implementation



# Web browser support

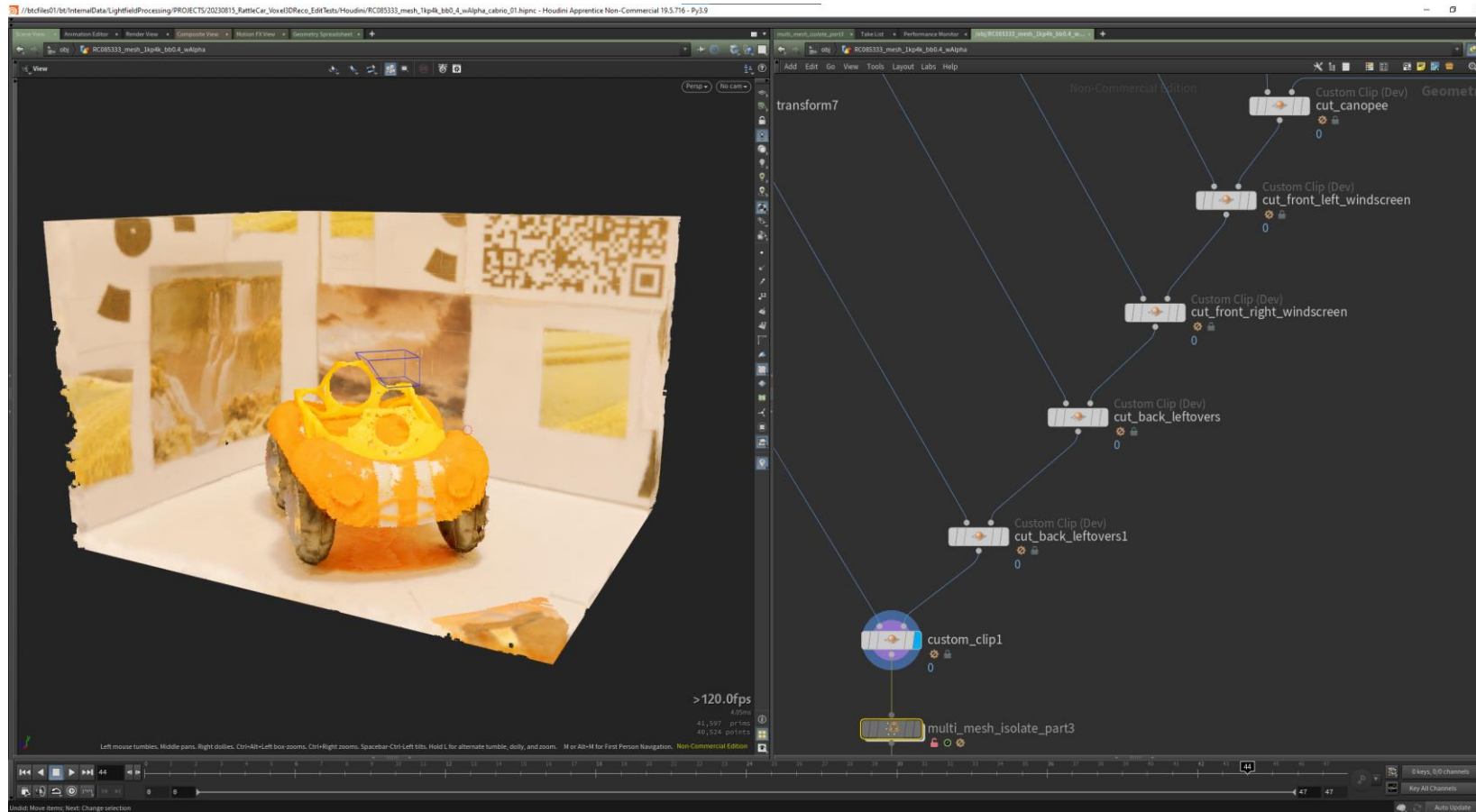
## WebGPU implementation

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# Voxel mesh editing

Use of standard 3D editing tools



# Voxel mesh editing

Rendering result





# The end

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## Contact

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XR Interaction Member (XR-INTERACTION.com)



- Research alliance for XR-technologies and applications
- Creation of publicly funded projects for basic technologies and applications
- Open for new complementary partners